

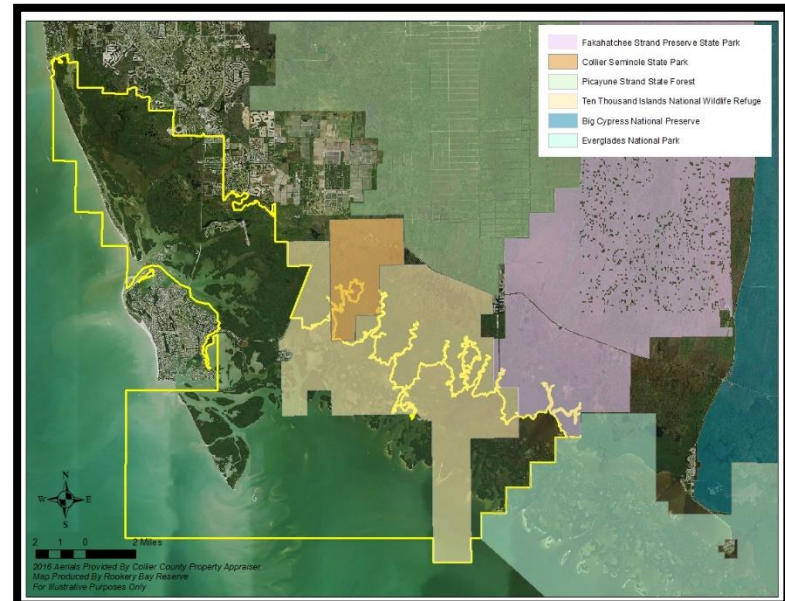
Mapping terrestrial and benthic habitat change to address mangrove and seagrass migration and die-off in response to recent and long-term environmental drivers

Project Leads: Frank Muller-Karger and Matt McCarthy

Collaborative Lead: Brita Jessen

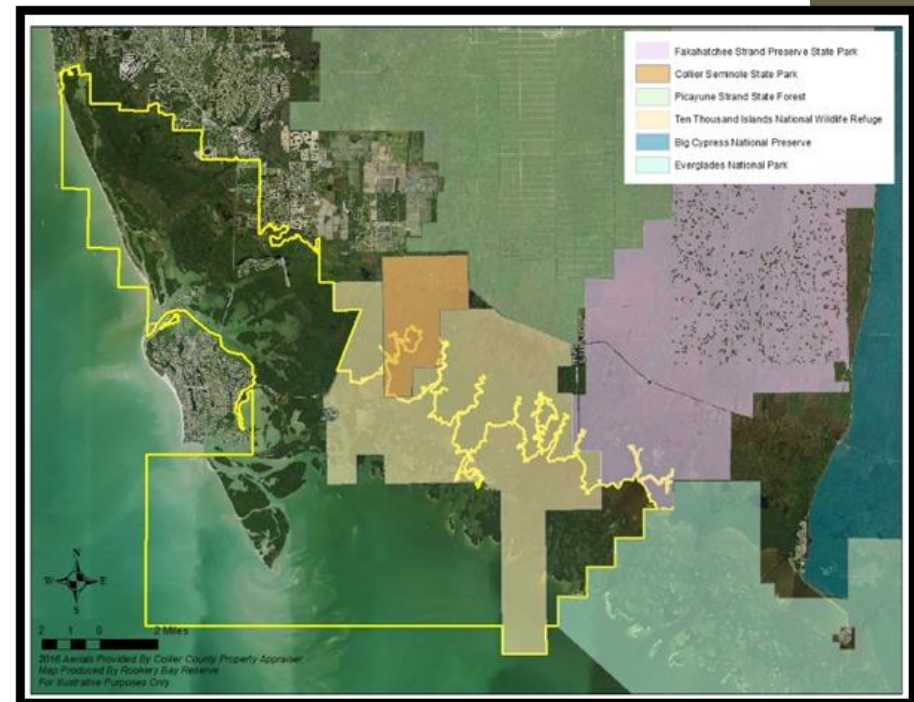
Team Members: Tylar Murray, Jill Schmid, Jessica McIntosh

Consultants: Mike Barry, Axiom Data Science



Rookery Bay Mapping

- Project Goals:
 - Map land and aquatic habitats throughout the reserve for years:
 - 2010, 2013, 2016, 2017, 2018
 - Data:
 - High-resolution and medium-resolution satellite imagery
 - Field surveys (M. Barry)



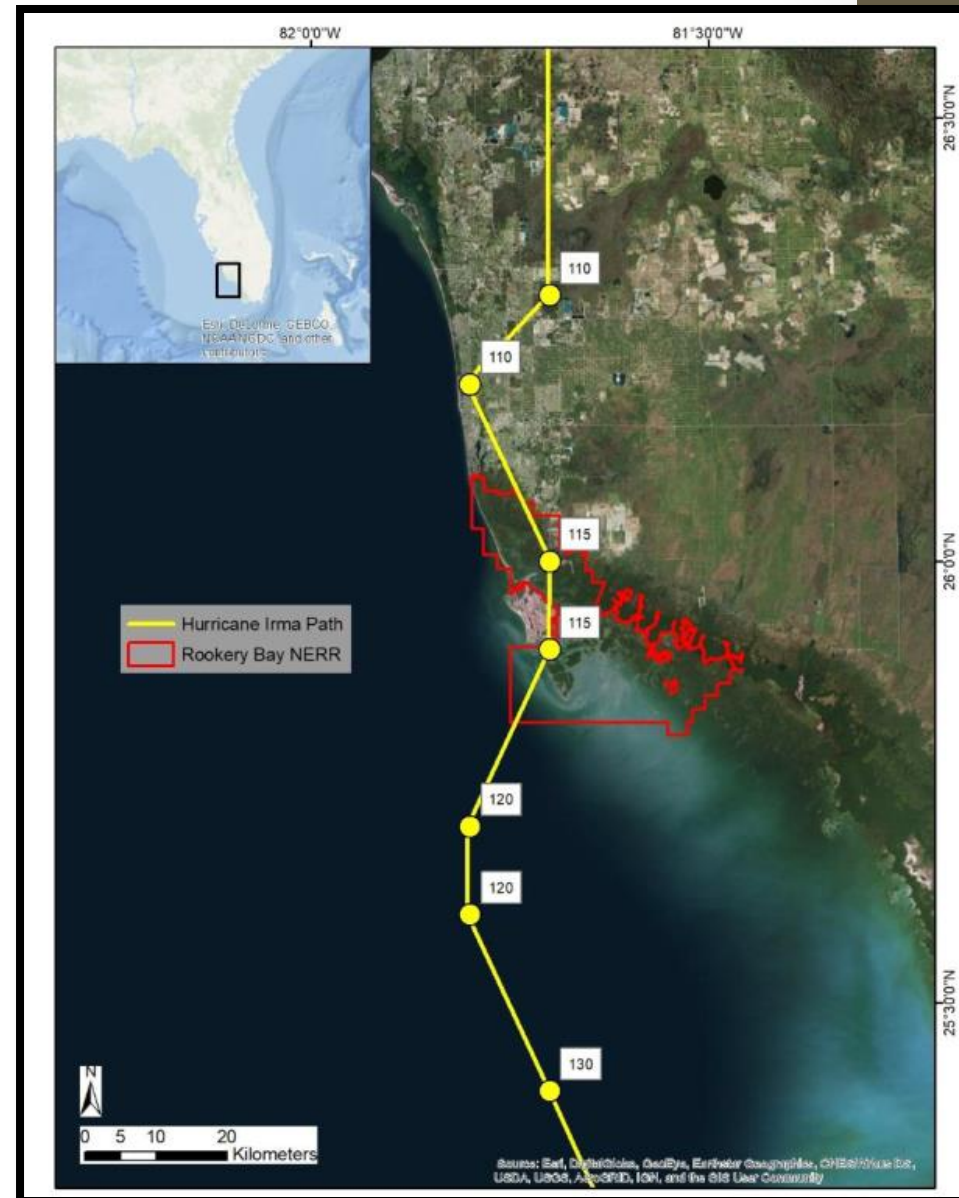
Purpose

- Management Need:
 - Identify location, extent, and severity of mangrove and seagrass degradation
 - Inform management how to mitigate loss and improve resiliency



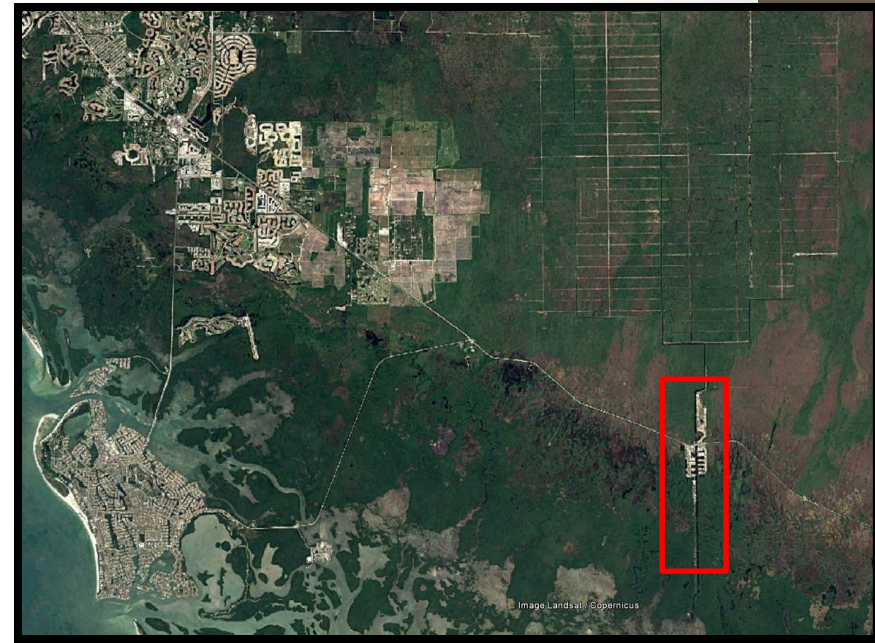
Purpose

- Habitat degradation causes:
 - Mangroves
 - Chronic hydrologic stress – road/highway construction, water diversion, sea level rise
 - Short-term events – Hurricane Irma
 - Seagrass
 - Boat scarring
 - Fragmentation



Background

- Ken Krauss et al. 2011
 - Ten Thousand Islands NWR
 - Sea-level rise and freshwater flow alteration drive mangrove migration inland
 - Mangrove coverage increased 35% 1927-2005
 - Marsh lost
 - Caused by development: canals, roads, houses
 - Recommend return to natural, overland freshwater flow



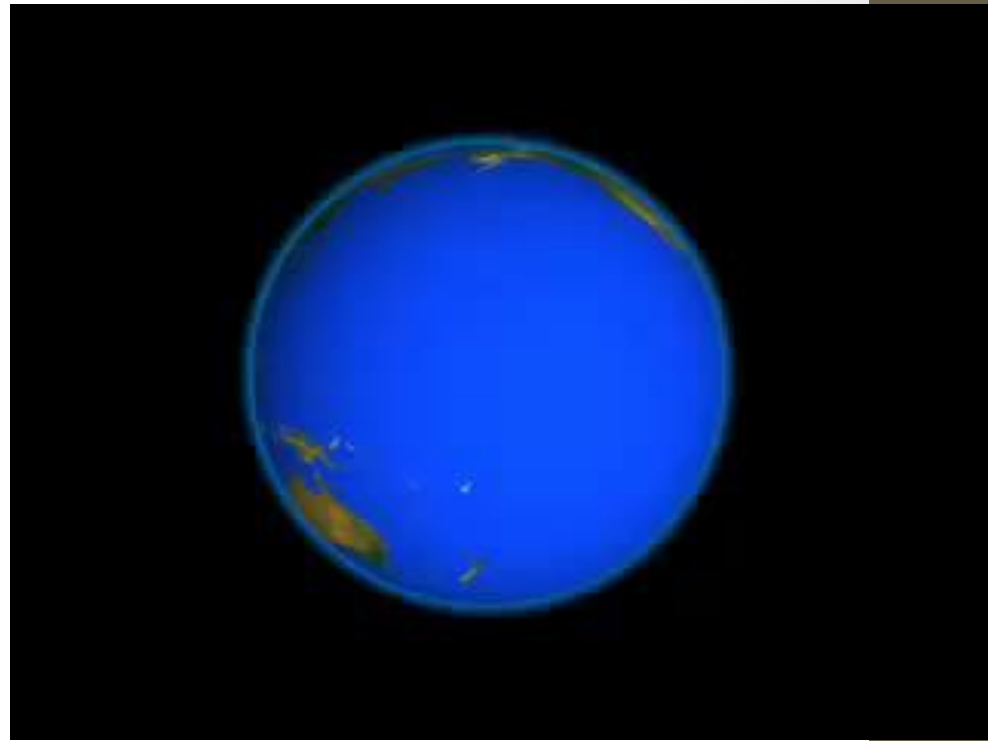
Background

- Lewis et al. 2016
 - Long-term stress + acute events = rapid die-off
 - Loss can occur in just a few years
 - Mangrove heart attack prevention
 - Stress must be detected early
 - Cause: impaired water flow
 - Requires large-scale monitoring
 - Satellite or aerial mapping
 - Ground-truthing



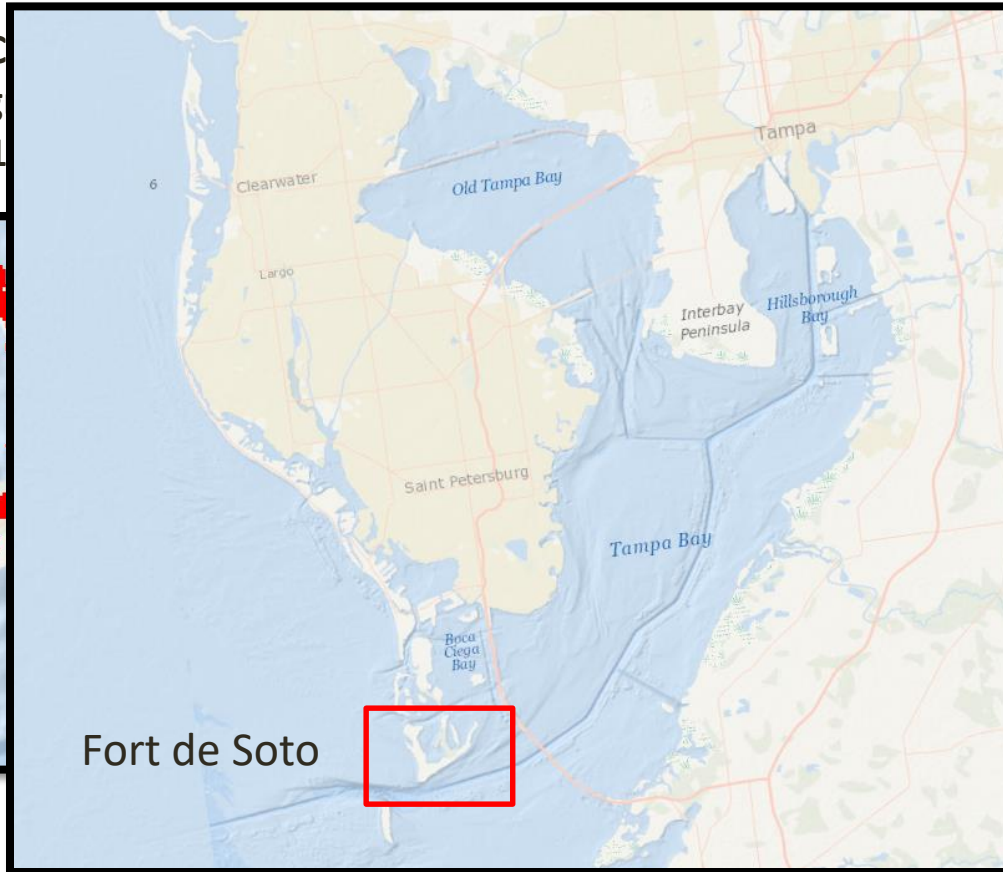
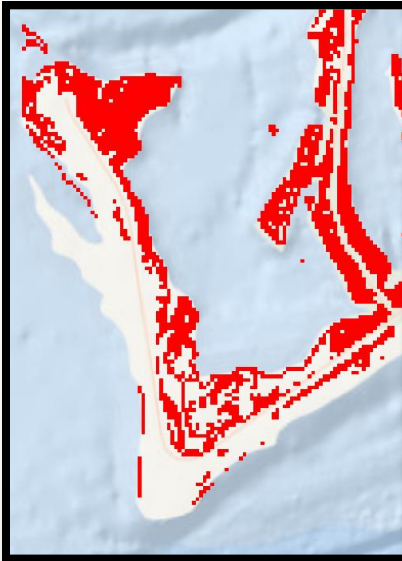
Methods

- Wetland classification challenges:
 - Misclassification with adjacent vegetation
 - Sparse Aerial Imagery
 - Spatial Resolution



Wetland Map Inconsistencies

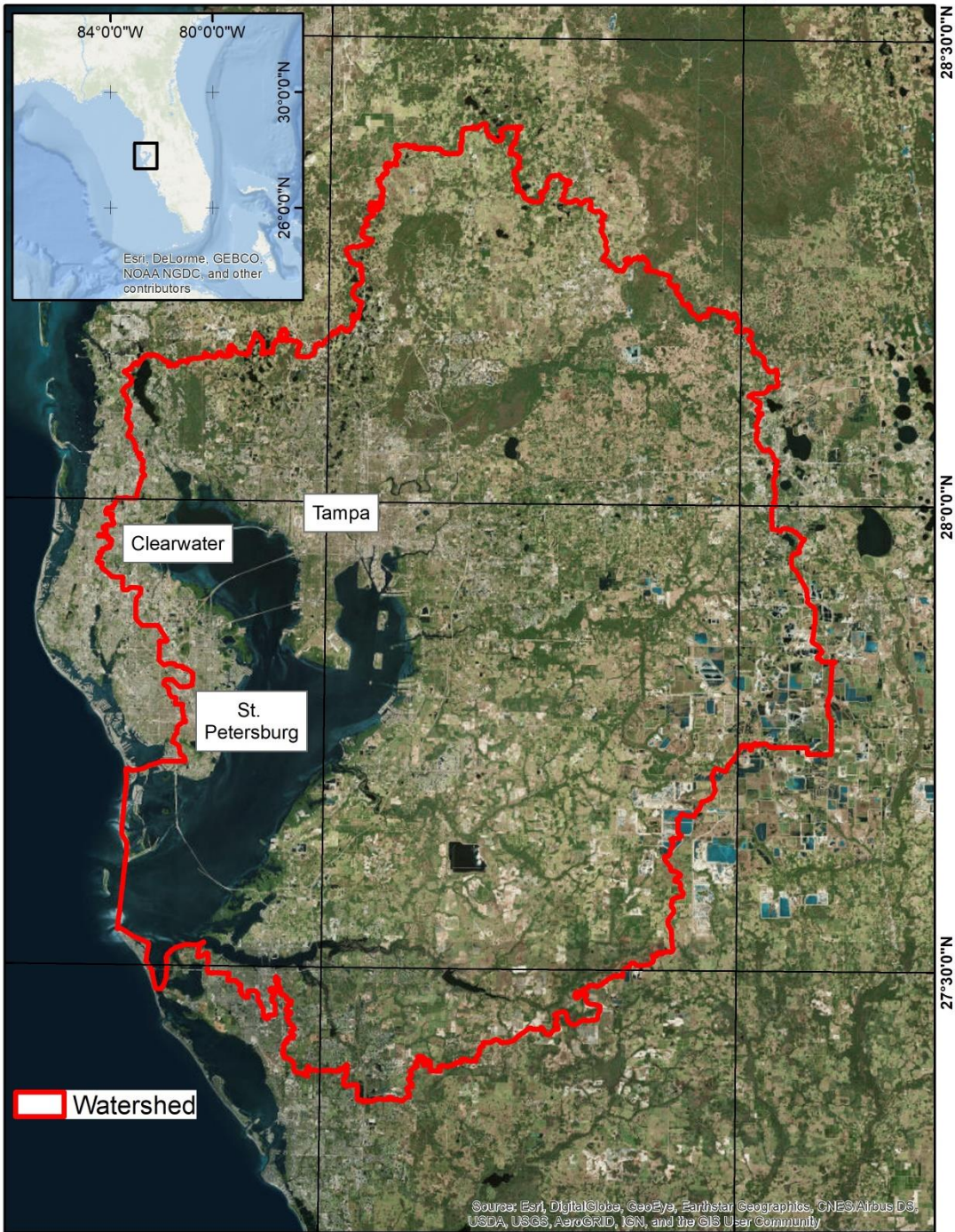
NOAA Coastal Change
Analysis Program
(CCAP) 2011



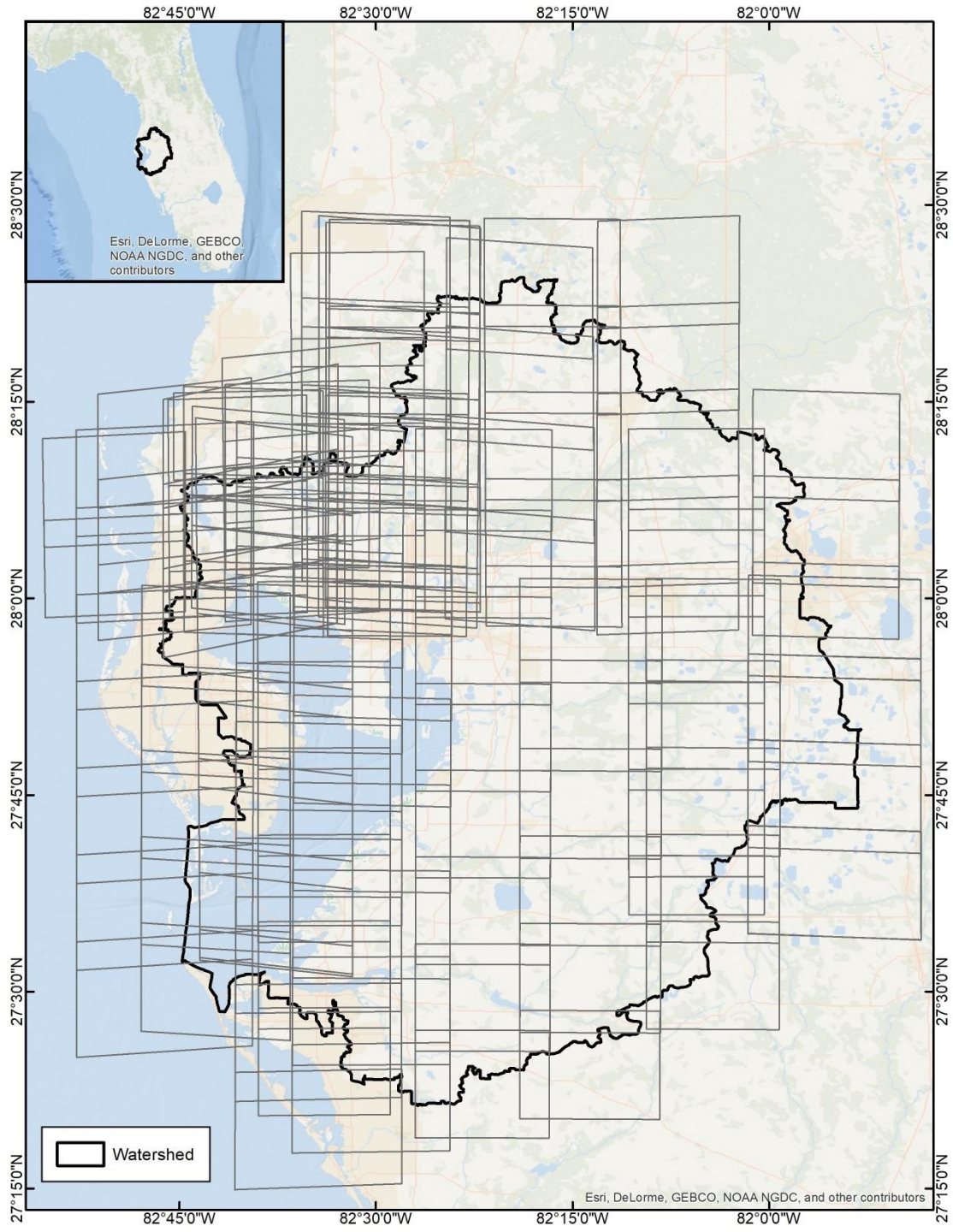
Fort de Soto

National Wetland
Inventory
(NWI) 2009






130
WorldView-2
Images



How to Improve Classifications?

- Use satellite-images:
 - Continual monitoring
 - Objective and ***Efficient***
 - Digital data = automated classification methods
- Use high-resolution imagery:
 - More detail = higher precision & greater accuracy






Contents lists available at [ScienceDirect](#)


Remote Sensing of Environment

journal homepage: www.elsevier.com/locate/rse



Enabling efficient, large-scale high-spatial resolution wetland mapping using satellites

Matthew J. McCarthy^{a,b,*}, Kara R. Radabaugh^b, Ryan P. Moyer^b, Frank E. Muller-Karger^a



Automated Mapping

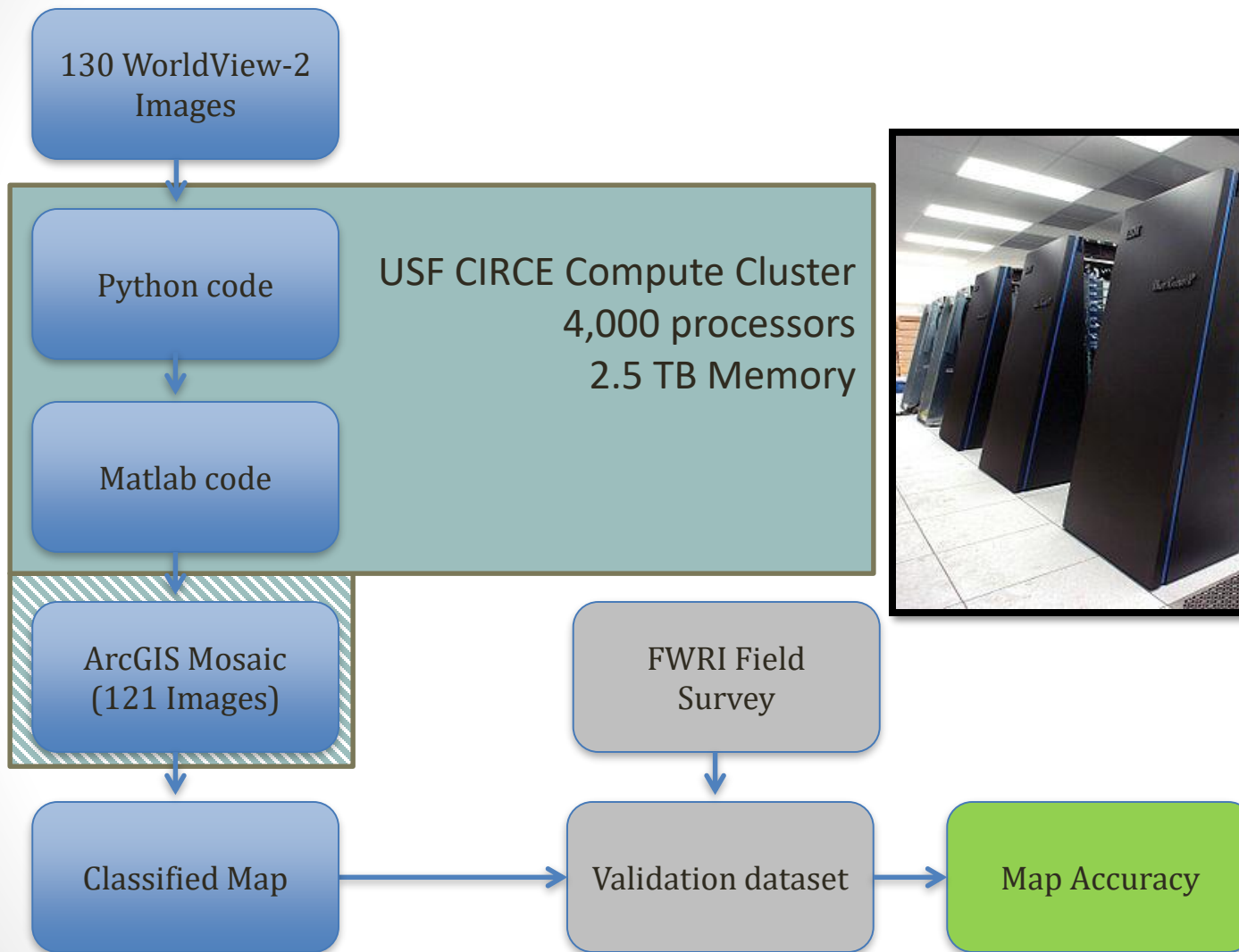
- Step 1:

- Python: pgc_ortho code
 - Developed by the Polar Geospatial Center
 - Loads NITF WorldView-2 images
 - Projects image to user-defined projection
 - Outputs a GeoTIFF
- Time: 17 seconds/image

- Step 2:

- Matlab: new code
 - Loads GeoTIFFs and metadata
 - Radiometrically calibrates image
 - Corrects for atmosphere
 - Converts to remote-sensing reflectance
 - Classifies image using Decision Tree
 - Smooths image through moving window filter
 - Outputs a classified GeoTIFF
- Time: ~10 mins/image w/ filter
~1 min/image w/o filter

Methodology

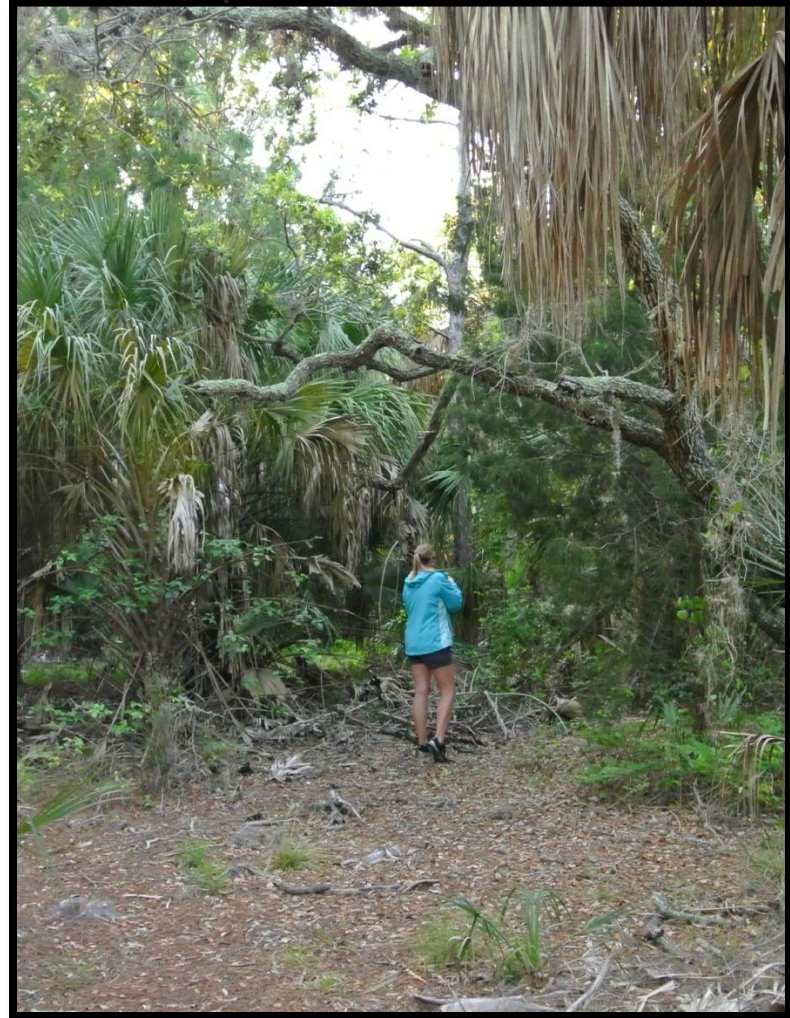


Field Survey

Wetlands



Upland Forest



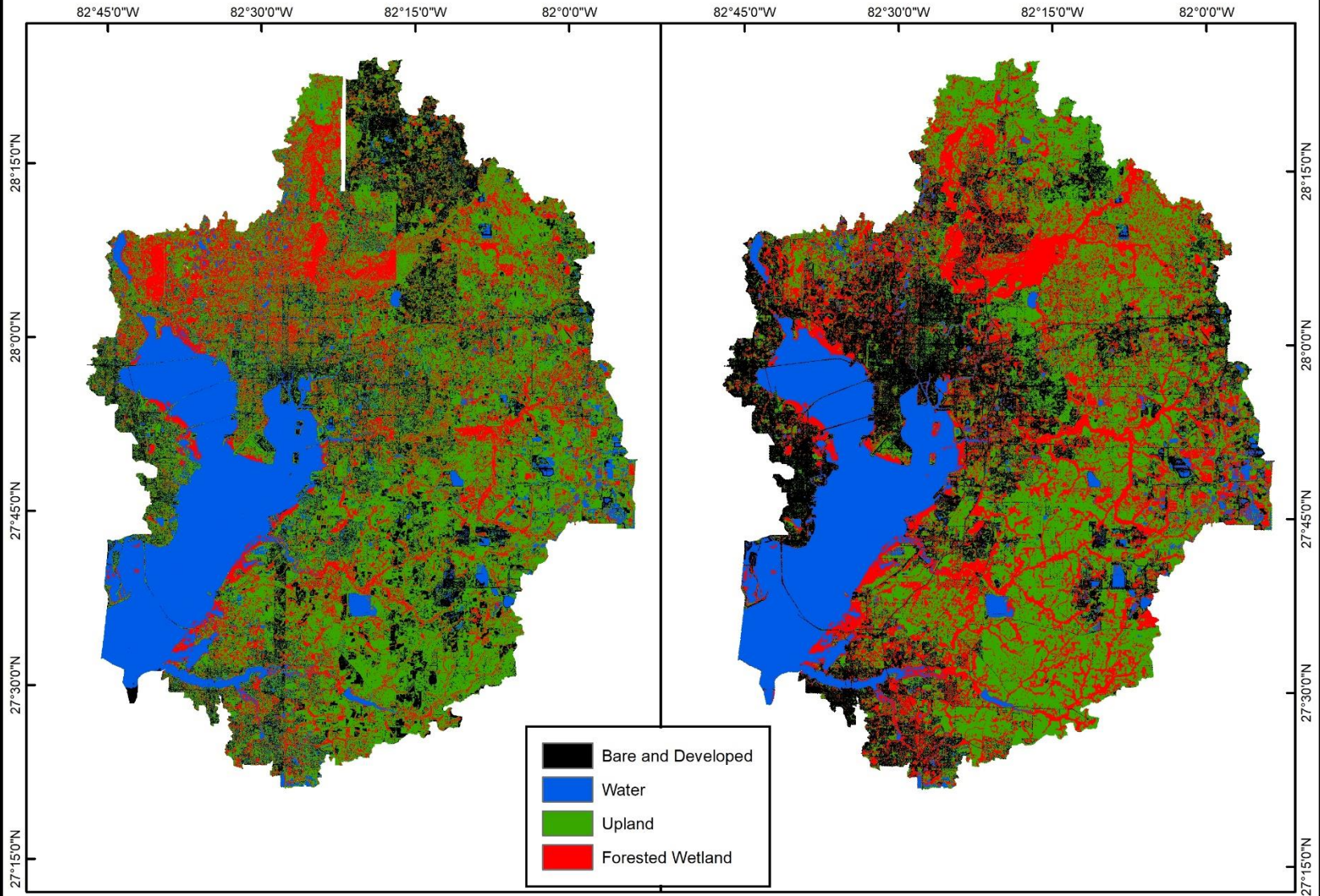
Results: Map Accuracy

| | Upland Accuracy | Wetland Accuracy |
|-----------|------------------------|-------------------------|
| CCAP 2010 | 19% | 62% |
| IMaRS | 63% | 81% |

Results: Map Comparison

IMaRS (WorldView-2)
6584 sq km

NOAA CCAP (Landsat)
6586 sq km

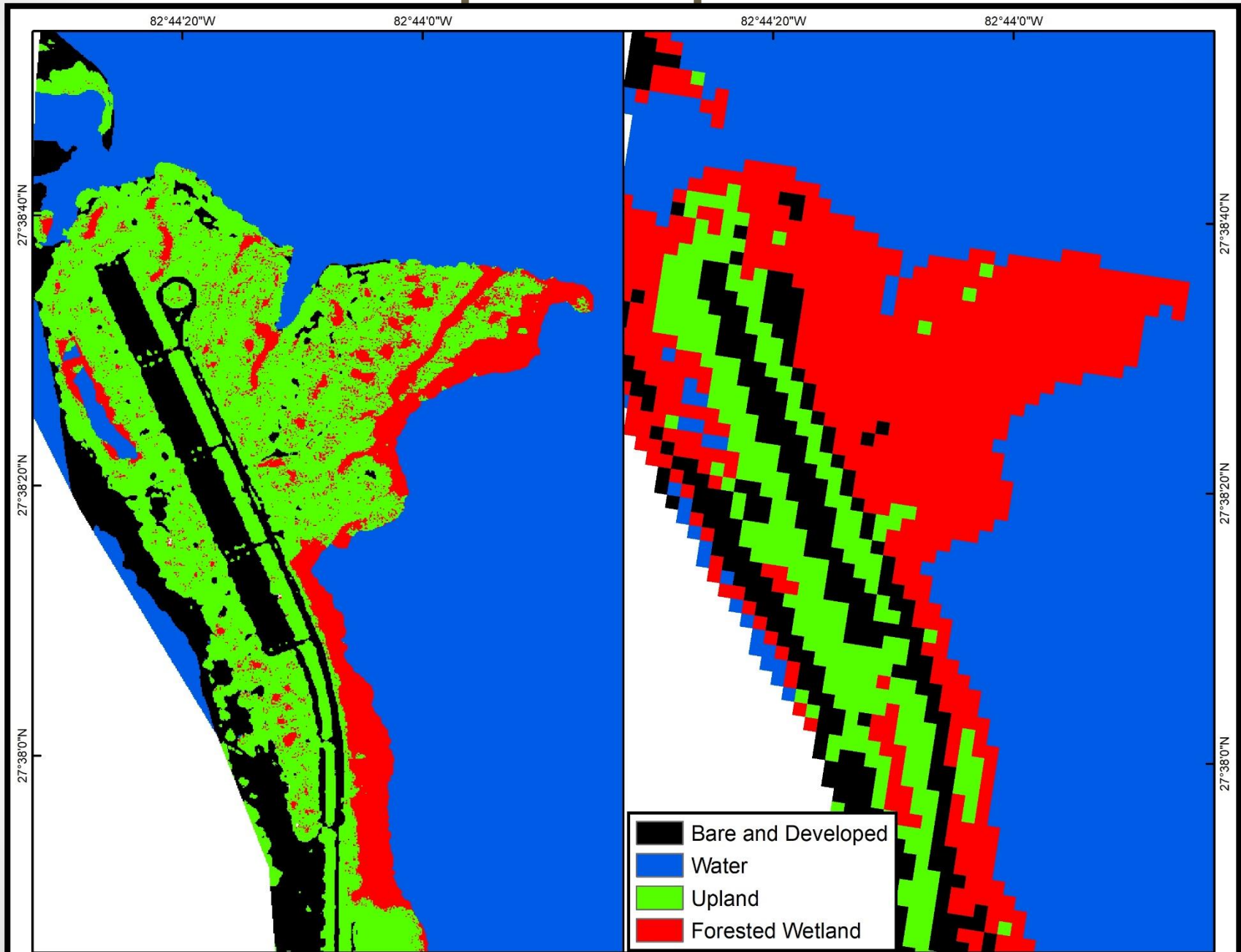


Results: Vegetation Area

| | Upland Area (km ²) | | Wetland Area (km ²) | |
|------------------|--------------------------------|--------|---------------------------------|--------|
| | IMaRS | NOAA | IMaRS | NOAA |
| Watershed | 3134.9 | 2069.3 | 1455.7 | 1679.3 |

| | IMaRS (km ²) | NOAA (km ²) | Difference (km ²) |
|--------------------------|--------------------------|-------------------------|-------------------------------|
| Total vegetation: | 4590.6 | 3748.6 | 841.9 |

Results: Map Comparison

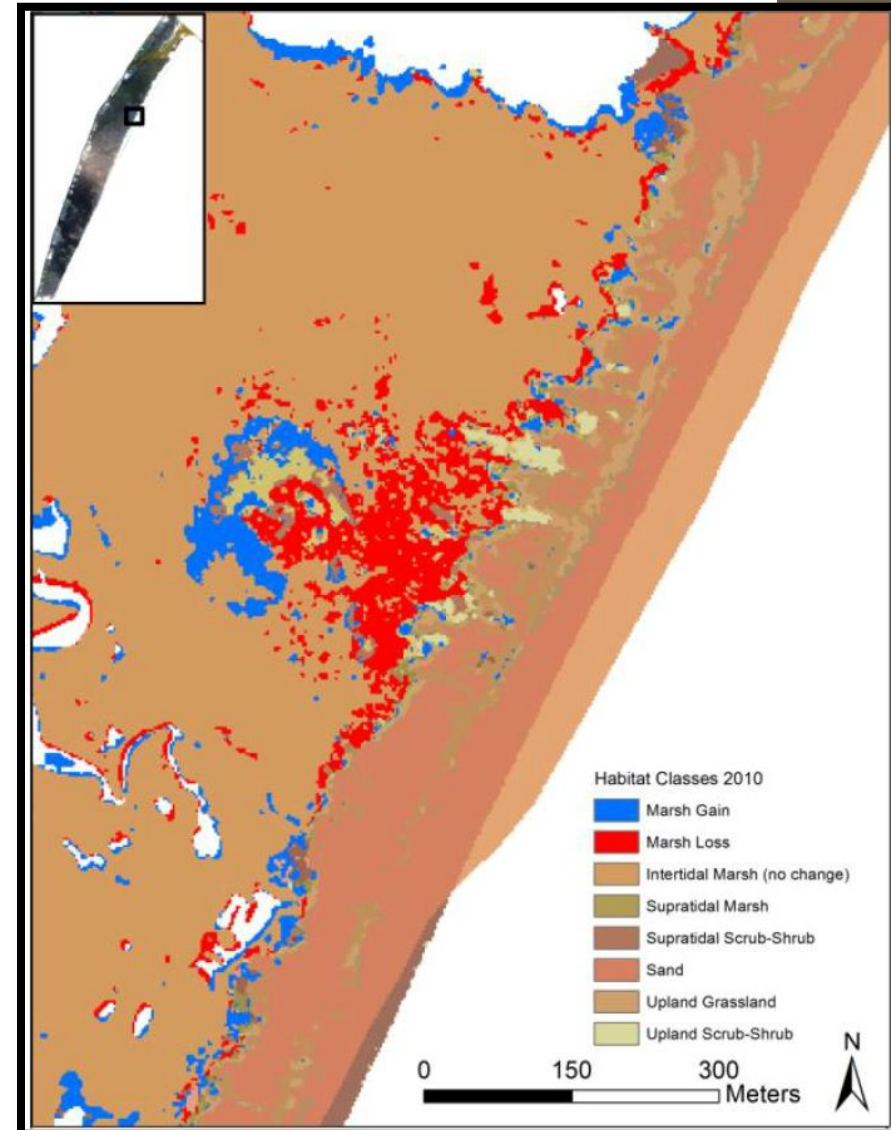


Rookery Bay Mapping

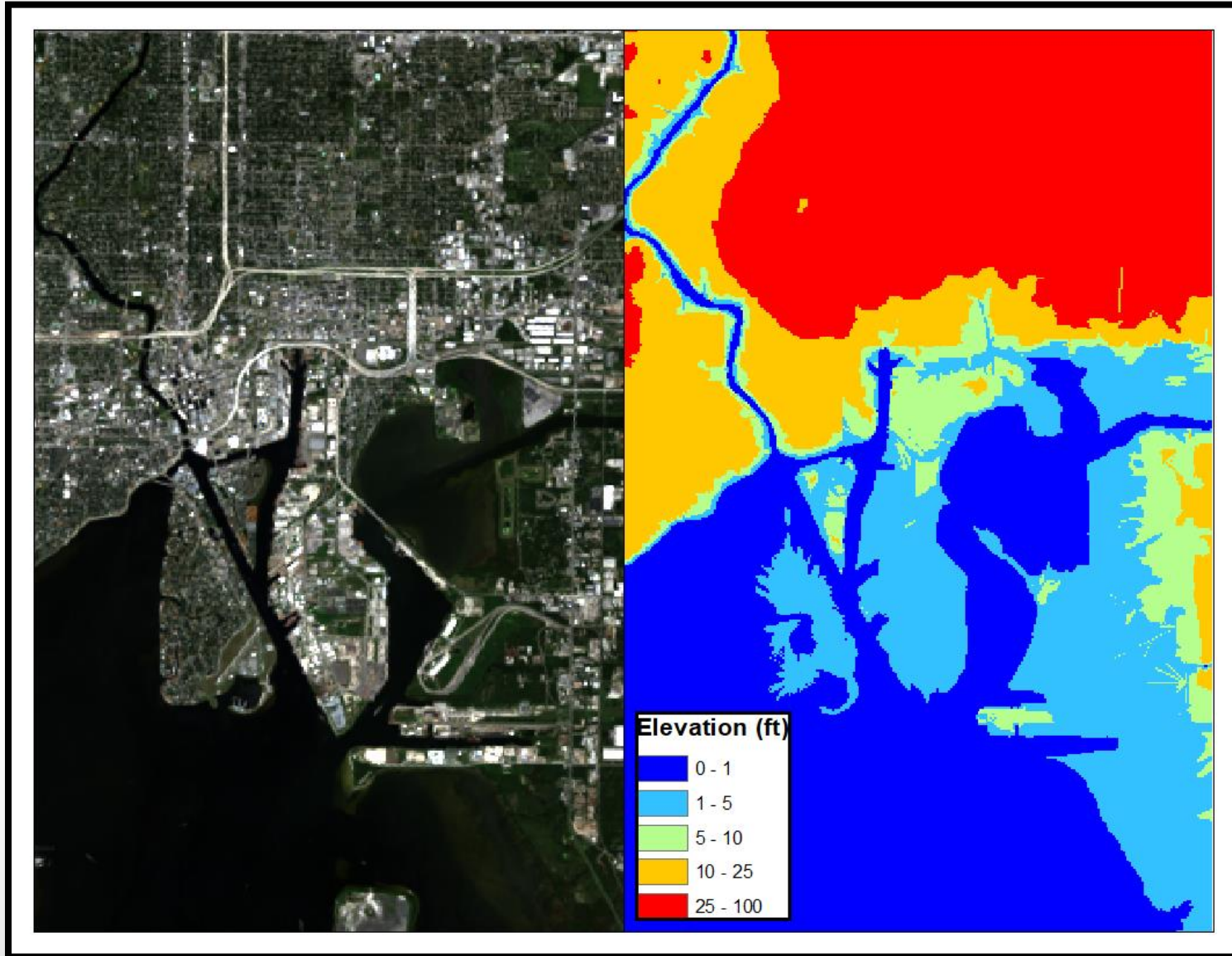
- Project Goals:
 1. Map land and aquatic habitats throughout the reserve for years:
 - 2-meter: 2010, 2016, 2017, 2018
 - 30-meter: 2013, 2016, 2017, 2018
 - Target Habitats
 - Seagrass
 - Sand/Mud bottom
 - Hard bottom
 - Forested Mangrove
 - Marsh Grass
 - Beach
 - Salt Flat
 - Upland Vegetation
 - Developed
 2. **Assess Change**

Rookery Bay Mapping

- Change Detection
 - 2010-2016 (2013-2016)
 - 2016-2017
 - 2017-2018
 - Early 2018 – Late 2018(?)
- Hydrology Mapping



Rookery Bay Mapping

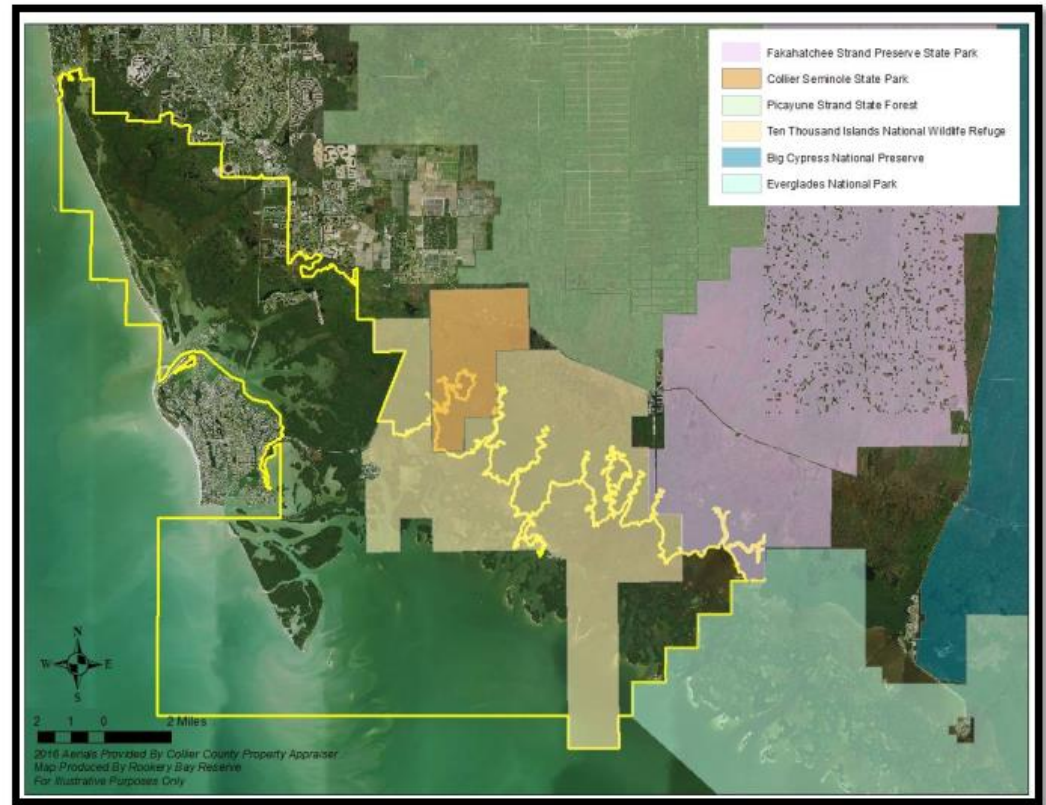


Rookery Bay Mapping



Rookery Bay Mapping

- End-Users
 - RBNERR
 - Ten Thousand Islands National Wildlife Refuge
 - USGS
 - US Marine Biodiversity Observation Network



Rookery Bay Mapping

- Benefits & Outputs
 - More efficient mapping protocol
 - Annual habitat maps
 - 2-meter
 - 30-meter
 - Interannual change detection
 - Location and extent of degradation or recovery
 - Hydrologic model of RBNERR
 - New collaborative relationships
 - Open Access to all products
 - Axiom Data Science web portal

Acknowledgements

- NASA Marine Biodiversity Observation Network
- NSF 3D Wetland Spoke
- Microsoft Artificial Intelligence for Earth

